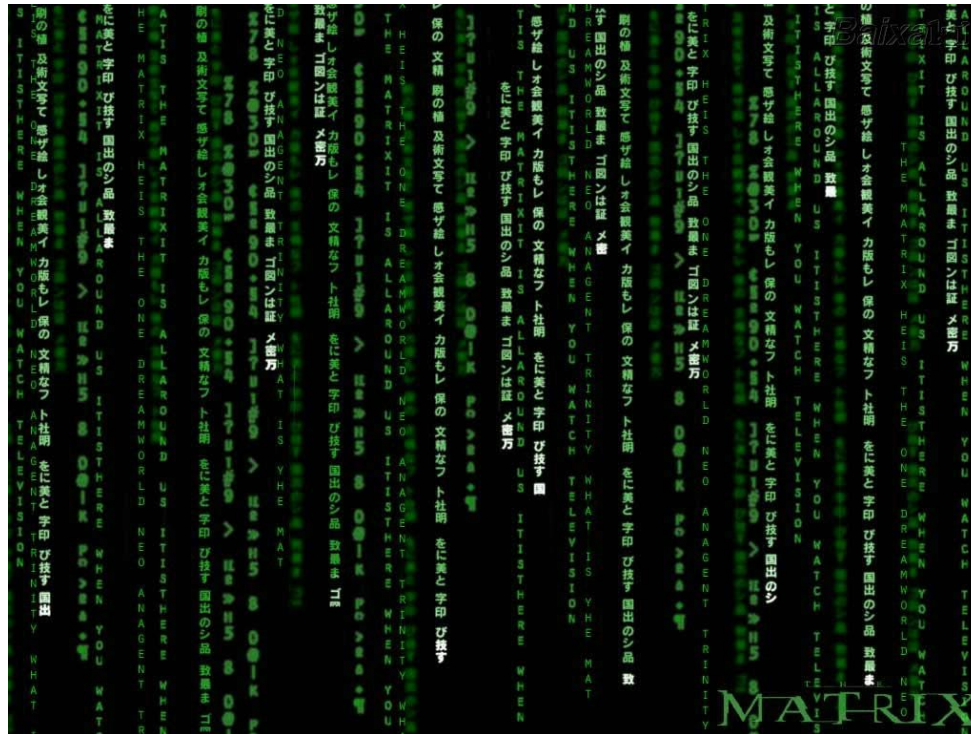


Matrices



ma'trix *n.* (*pl.* ~ices or ~ixes) **5.** (Math.) rectangular array of quantities in rows and columns that is treated as a single quantity.

$$\mathbf{A} = \begin{pmatrix} 1 & -2 & 0 \\ 9 & 1 & 2 \\ 1 & 3 & 4 \end{pmatrix}$$



A matrix is a rectangular array of numbers.

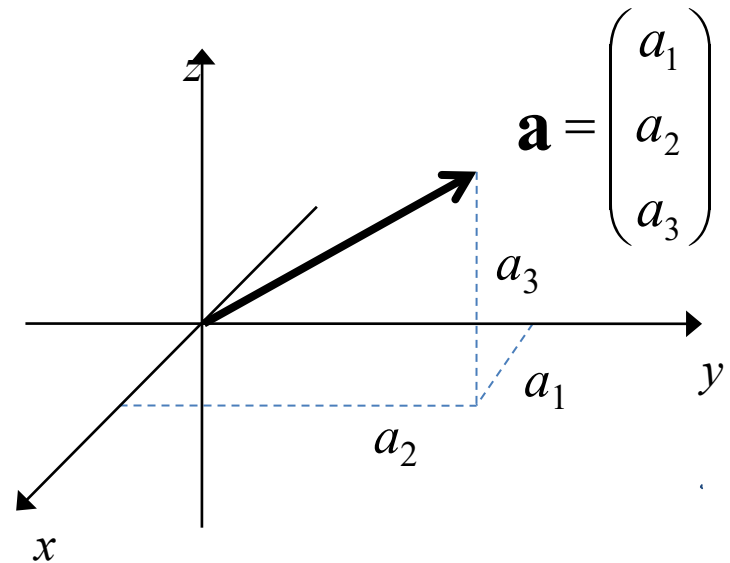
$$\mathbf{A} = \begin{pmatrix} 1 & -2 & 0 \\ 9 & 1 & 2 \\ 1 & 3 & 4 \end{pmatrix}$$

$$\mathbf{M} = \begin{pmatrix} 2 & 6 & -2 & 3 \\ -1 & 5 & 0 & 7 \end{pmatrix}$$

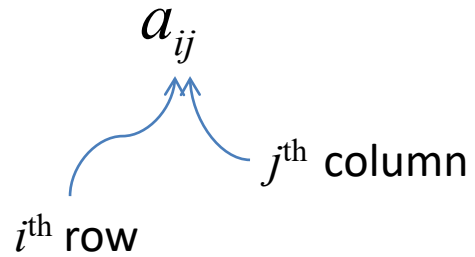
$$\mathbf{v} = \begin{pmatrix} 1 \\ -1 \\ 5 \\ 2 \\ -3 \end{pmatrix}$$

A matrix has order $m \times n$ if it has m rows and n columns.

A $(1 \times n)$ matrix is known as a *row vector*;
an $(m \times 1)$ matrix is called a *column vector*.



The *elements* of a matrix $\mathbf{A}$ are often written


$$a_{ij}$$

i^{th} row j^{th} column

Eg:

$$\mathbf{A} = \begin{pmatrix} 1 & -2 & 0 \\ 9 & 1 & 2 \\ 1 & 3 & 4 \end{pmatrix}$$

$$\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$$

If two matrices are *the same order*, they may be added or subtracted.

$$\begin{pmatrix} 2 & 1 \\ 1 & 0 \\ -1 & 3 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 2 & 1 \\ 3 & 1 \end{pmatrix} =$$

$$\begin{pmatrix} 1 & 3 & 6 & 1 \\ -1 & 1 & 2 & 1 \end{pmatrix} - \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix} =$$

$$\begin{pmatrix} 2 & 1 \\ 1 & 0 \\ -1 & 3 \end{pmatrix} + \begin{pmatrix} 1 & 3 & 6 & 1 \\ -1 & 1 & 2 & 1 \end{pmatrix} =$$

It follows that matrices are *commutative* and *associative* under addition:

$$\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$$

$$\mathbf{A} + (\mathbf{B} + \mathbf{C}) = (\mathbf{A} + \mathbf{B}) + \mathbf{C}$$

A zero matrix is any matrix with all elements equal to zero, and is usually written **0**:

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\mathbf{A} + \mathbf{0} = \mathbf{0} + \mathbf{A} = \mathbf{A}$$

It is straightforward to multiply matrices by a scalar quantity k :

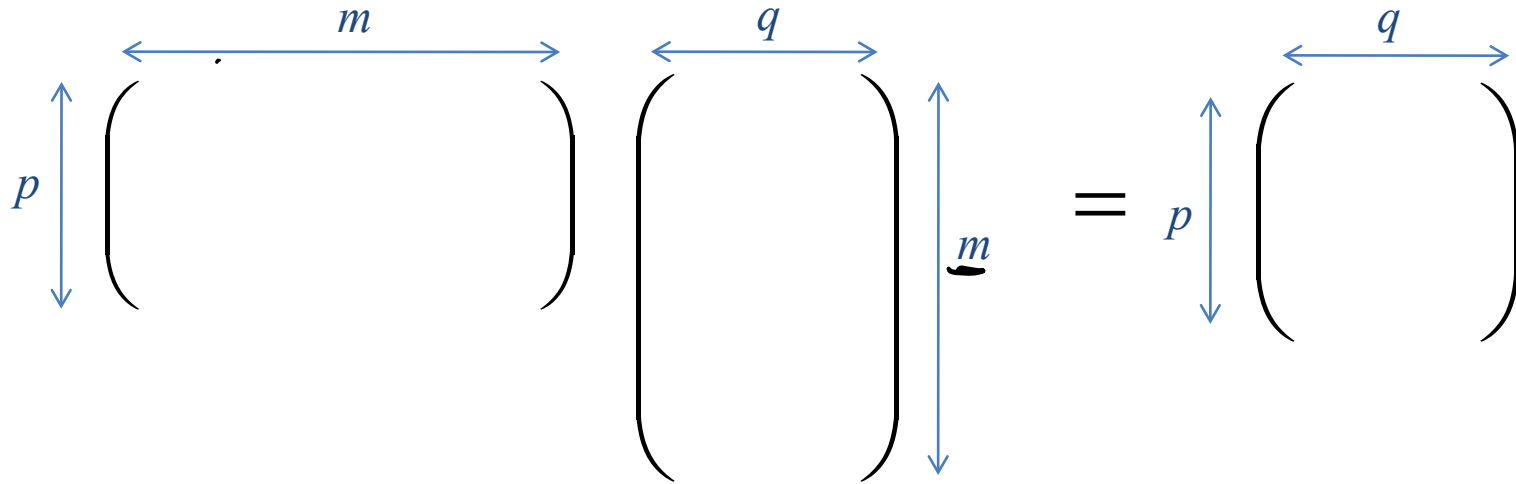
$$k \begin{pmatrix} 2 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 2k & k & 0 \\ k & k & k \\ 0 & k & 2k \end{pmatrix}$$

Multiplying two matrices together is more complicated.

$$\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \quad \mathbf{B} = \begin{pmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{pmatrix}$$

Rule: the number of columns of the first matrix must equal the number of rows of the second.

Rule: the number of columns of the first matrix must equal the number of rows of the second.



Multiplication of two matrices can be written as a sum:

$$[\mathbf{AB}]_{ij} = \sum_{k=1}^m \underline{a_{ik}} \underline{b_{kj}}$$

We define the product of a row vector and a column vector as being the sum of the components, added together. E.g:

$$(1 \quad -2 \quad 0) \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} =$$

$$\begin{pmatrix} \boxed{1} & -2 & 0 \\ 0 & 1 & 2 \\ 1 & 3 & 2 \end{pmatrix} \begin{pmatrix} \boxed{1} & 0 & 1 \\ \boxed{1} & 1 & 3 \\ \boxed{2} & 0 & 2 \end{pmatrix} = \begin{pmatrix} \boxed{} & \boxed{} & \boxed{} \\ \boxed{} & \boxed{} & \boxed{} \\ \boxed{} & \boxed{} & \boxed{} \end{pmatrix}$$

$$\mathbf{AB} = \begin{pmatrix} 3 & 1 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} = \begin{pmatrix} 3 & 1 & 5 \\ 1 & 1 & 1 \\ 0 & 1 & 4 \end{pmatrix}$$

If the matrices have the “wrong” dimensions for multiplication, then the product *does not exist*. E.g:

$$\begin{pmatrix} 2 & 1 \\ 1 & 0 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 3 & 2 & 0 \\ 2 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 3 & 6 & 1 \\ -1 & 1 & 2 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 1 & 0 \\ -1 & 3 \end{pmatrix}$$

Matrix multiplication is *non-commutative*, i.e. Usually,

$$\mathbf{AB} \neq \mathbf{BA}$$

$$\mathbf{AB} = \begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 1 & 1 \end{pmatrix} =$$

$$\mathbf{BA} = \begin{pmatrix} 2 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} =$$

Matrix Algebra

Most rules for manipulating matrices are *the same* as those for regular numbers.

Equality:

If $\mathbf{A} = \mathbf{B}$ and $\mathbf{A} = \mathbf{C}$ then $\mathbf{B} = \mathbf{C}$

Associativity under addition:

$$\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$$

$$(\mathbf{A} + \mathbf{B}) + \mathbf{C} = \mathbf{A} + (\mathbf{B} + \mathbf{C})$$

Matrix multiplication is *associative*

$$\mathbf{A}(\mathbf{BC}) = (\mathbf{AB})\mathbf{C}$$

but is *non-commutative*, i.e. Usually,

$$\mathbf{AB} \neq \mathbf{BA}$$

$$\begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} \quad \checkmark$$

Matrix multiplication has some other “strange” properties:

1. $\mathbf{AB} = \mathbf{0}$ does not necessarily mean that $\mathbf{A} = \mathbf{0}$ or $\mathbf{B} = \mathbf{0}$

$$\mathbf{AB} = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ -2 & 0 \end{pmatrix} =$$

2. $\mathbf{AD} = \mathbf{AC}$ does not necessarily mean that $\mathbf{D} = \mathbf{C}$

$$\mathbf{AD} = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 3 & 0 \\ -3 & 0 \end{pmatrix}$$

The identity matrix **I** is the matrix with the property

$$\mathbf{AI} = \mathbf{IA} = \mathbf{A}$$

$$\mathbf{I} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 3 & 1 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 3 & 1 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 2 \end{pmatrix}$$

The Inverse of a square matrix

The inverse of a square matrix $\mathbf{A}$ (written $\mathbf{A}^{-1}$) has the property that

$$\mathbf{A}^{-1} \mathbf{A} = \mathbf{I} \quad \text{and} \quad \mathbf{A} \mathbf{A}^{-1} = \mathbf{I}$$

A matrix only has *one* inverse.

$$\mathbf{A} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad \mathbf{A}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} \quad \det \mathbf{A} = ad - bc$$

$$\mathbf{A} = \begin{pmatrix} 3 & -1 \\ 2 & 2 \end{pmatrix}$$

The *transpose* of a matrix is obtained by interchanging the rows and the columns:

$$\mathbf{A} = \begin{pmatrix} 2 & 6 & -2 & 3 \\ -1 & 5 & 0 & 7 \end{pmatrix}$$

$$\mathbf{B} = \begin{pmatrix} 2 & 1 \\ 5 & 0 \\ -1 & 3 \end{pmatrix}$$

If A and B have the same order,

$$(\mathbf{A} + \mathbf{B})^T = \mathbf{A}^T + \mathbf{B}^T$$

$$(\mathbf{A}^T)^T = \mathbf{A}$$

$$(\mathbf{AB})^T = \mathbf{B}^T \mathbf{A}^T$$

$$\mathbf{A}^T = \begin{pmatrix} 2 & -1 \\ 6 & 5 \\ -2 & 0 \\ 3 & 7 \end{pmatrix}$$

Summary: Rules of matrix algebra

Equality:

If $\mathbf{A} = \mathbf{B}$ and $\mathbf{A} = \mathbf{C}$ then $\mathbf{B} = \mathbf{C}$

Addition:

$$\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$$

$$(\mathbf{A} + \mathbf{B}) + \mathbf{C} = \mathbf{A} + (\mathbf{B} + \mathbf{C})$$

Multiplication:

$$(\mathbf{A} + \mathbf{B}) \mathbf{C} = \mathbf{AC} + \mathbf{BC}$$

$$k(\mathbf{A} + \mathbf{B}) = k\mathbf{A} + k\mathbf{B}$$

$$k(\mathbf{AB}) = (k\mathbf{A}) \mathbf{B}$$

Special matrices:

$$\mathbf{AI} = \mathbf{IA} = \mathbf{A}$$

$$\mathbf{A} + \mathbf{0} = \mathbf{A}$$

If $\mathbf{A}$ has an inverse,

$$\mathbf{A}^{-1} \mathbf{A} = \mathbf{A} \mathbf{A}^{-1} = \mathbf{I}$$

Transposes:

$$(\mathbf{A} + \mathbf{B})^T = \mathbf{A}^T + \mathbf{B}^T$$

$$(\mathbf{AB})^T = \mathbf{B}^T \mathbf{A}^T$$

Remember that in general:

$$\mathbf{AB} \neq \mathbf{BA}$$

$\mathbf{AB} = \mathbf{0}$ does not necessarily mean that $\mathbf{A} = \mathbf{0}$ or $\mathbf{B} = \mathbf{0}$

$\mathbf{AD} = \mathbf{AC}$ does not necessarily mean that $\mathbf{D} = \mathbf{C}$

Main uses of matrices:

Numerical simulations, image processing, solving linear systems of equations ...

Solving systems of Equations

Matrices are very useful for representing systems of linear equations.

E.g. Suppose we want to solve

$$2x + 3y = 5$$

$$x - 7y = 1$$

Overview:

To solve the system

$$2x_1 + 3x_2 = 5$$

$$x_1 - 7x_2 = 1$$

Write in matrix form:

$$\begin{pmatrix} 2 & 3 \\ 1 & -7 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 5 \\ 1 \end{pmatrix}$$

Multiply *on the left* by the inverse of the square matrix:

$$\begin{aligned} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} &= \begin{pmatrix} 2 & 3 \\ 1 & -7 \end{pmatrix}^{-1} \begin{pmatrix} 5 \\ 1 \end{pmatrix} \\ &= \frac{1}{-17} \begin{pmatrix} -7 & -3 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} 5 \\ 1 \end{pmatrix} = \frac{1}{17} \begin{pmatrix} 38 \\ 3 \end{pmatrix} = \begin{pmatrix} \frac{38}{17} \\ \frac{3}{17} \end{pmatrix} \end{aligned}$$

$$\mathbf{A}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

$$\det \mathbf{A} = ad - bc$$

Example:

Solve the linear system

$$5x_1 - 10x_2 = 3$$

$$2x_1 + 3x_2 = 5$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 5 & -10 \\ 2 & 3 \end{pmatrix}^{-1} \begin{pmatrix} 3 \\ 5 \end{pmatrix} =$$

$$\frac{1}{15 - 2 \times (-10)} \begin{pmatrix} 3 & 10 \\ -2 & 5 \end{pmatrix} \begin{pmatrix} 3 \\ 5 \end{pmatrix} =$$

$$= \frac{1}{35} \begin{pmatrix} 3 \times 3 + 10 \times 5 \\ -2 \times 3 + 5 \times 5 \end{pmatrix} = \frac{1}{35} \begin{pmatrix} 59 \\ 19 \end{pmatrix}$$

Cramer's Formula

$$\begin{array}{rclcl} 5x_1 & - & 10x_2 & = & 3 \\ 2x_1 & + & 3x_2 & = & 5 \end{array} \Leftrightarrow \begin{pmatrix} 5 & -10 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 3 \\ 5 \end{pmatrix}, \quad \mathbf{Ax} = \mathbf{b}$$

$$\mathbf{A} = \begin{pmatrix} 5 & -10 \\ 2 & 3 \end{pmatrix}, \quad D = \det \mathbf{A} = 5 \times 3 - (-10) \times 2 = 35 \quad \text{D is the determinant of matrix } \mathbf{A}.$$

$$D_1 = \det \begin{pmatrix} 3 & -10 \\ 5 & 3 \end{pmatrix} = 3 \times 3 - (-10) \times 5 = 59$$

Replace first column of matrix $\mathbf{A}$ with column vector $\mathbf{b}$ and find the determinant D_1 .

$$D_2 = \det \begin{pmatrix} 5 & 3 \\ 2 & 5 \end{pmatrix} = 5 \times 5 - 3 \times 2 = 19$$

Replace the second column of matrix $\mathbf{A}$ with column vector $\underline{b}$ and find the determinant D_2 .

$$x_1 = \frac{D_1}{D} = \frac{59}{35},$$

$$x_2 = \frac{D_2}{D} = \frac{19}{35}.$$

Determinants of 3x3 matrices

The cofactors are the signed determinants of the small matrices.

$$\Delta = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

$$\Delta = a_{11}(a_{22}a_{33} - a_{23}a_{32}) - a_{12}(a_{21}a_{33} - a_{23}a_{31}) \\ + a_{13}(a_{21}a_{32} - a_{22}a_{31})$$

Steps to compute the determinant using cofactors:

1. Remove the top row (or first column)
2. Multiply the coefficients of this row with +, -, +, -, +, - etc...
3. Multiply the coefficients of this row with the determinant of the *minor matrix* i.e. the matrix obtained by deleting the coefficient's row and column

Determinants of 3x3 matrices

The determinant of a 3 x 3 matrix is given by the formula

$$\Delta = a_{11}(a_{22}a_{33} - a_{23}a_{32}) - a_{12}(a_{21}a_{33} - a_{23}a_{31}) \\ + a_{13}(a_{21}a_{32} - a_{22}a_{31})$$

and is often denoted by |square brackets| around the matrix.

Example: Calculate the determinant of $\begin{pmatrix} 1 & -2 & 2 \\ 1 & -2 & 1 \\ 3 & -2 & 1 \end{pmatrix}$

$$\det \begin{pmatrix} 1 & -2 & 2 \\ 1 & -2 & 1 \\ 3 & -2 & 1 \end{pmatrix} = 1 \begin{bmatrix} -2 & 1 \\ -2 & 1 \end{bmatrix} - (-2) \begin{bmatrix} 1 & 1 \\ 3 & 1 \end{bmatrix} + 2 \begin{bmatrix} 1 & -2 \\ 3 & -2 \end{bmatrix} = \\ = 2(1-3) + 2(-2+6) = 8-4 = 4$$

Example: Calculate the determinant of $\begin{pmatrix} 1 & 1 & 2 \\ 2 & -1 & 3 \\ 3 & -1 & -1 \end{pmatrix}$

$$\begin{aligned} \det \begin{pmatrix} 1 & 1 & 2 \\ 2 & -1 & 3 \\ 3 & -1 & -1 \end{pmatrix} &= 1 \begin{bmatrix} -1 & 3 \\ -1 & -1 \end{bmatrix} - \begin{bmatrix} 2 & 3 \\ 3 & -1 \end{bmatrix} + 2 \begin{bmatrix} 2 & -1 \\ 3 & -1 \end{bmatrix} = \\ &= (1 + 3) - (-2 - 9) + 2(-2 + 3) = 17 \end{aligned}$$

Tricks when dealing with determinants

If any row or column contains only zeros then the determinant is zero

e.g.

$$\begin{vmatrix} 1 & 3 & 5 \\ 1 & -2 & 3 \\ 0 & 0 & 0 \end{vmatrix}$$

If any two rows or columns are identical then the determinant is zero

e.g.

$$\begin{vmatrix} 1 & 3 & 5 \\ 1 & -2 & 3 \\ 1 & -2 & 3 \end{vmatrix}$$

To find the determinant of a matrix in *triagonal form*,
multiply down the diagonal

e.g.

$$\begin{vmatrix} 1 & 3 & 5 \\ 0 & -2 & 3 \\ 0 & 0 & 6 \end{vmatrix}$$

$$\begin{vmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{vmatrix}$$

Use Crammer's method to find the solution of linear system

$$\begin{array}{rrcr} x_1 & -2x_2 & +2x_3 & = & 1 \\ x_1 & -2x_2 & +x_3 & = & 1 \\ 3x_1 & -2x_2 & +x_3 & = & 1 \end{array}$$

$$\mathbf{A} = \begin{bmatrix} 1 & -2 & 2 \\ 1 & -2 & 1 \\ 3 & -2 & 1 \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{Ax} = \mathbf{b}$$

$$D = \det \mathbf{A} = \begin{vmatrix} 1 & -2 & 2 \\ 1 & -2 & 1 \\ 3 & -2 & 1 \end{vmatrix} = 4 \neq 0$$

$$D_1 = \begin{vmatrix} 1 & -2 & 2 \\ 1 & -2 & 1 \\ 1 & -2 & 1 \end{vmatrix} = 0$$

$$x_1 = \frac{D_1}{D} = 0$$

$$D_2 = \begin{vmatrix} 1 & \underline{1} & 2 \\ 1 & \underline{1} & 1 \\ 3 & \underline{1} & 1 \end{vmatrix} = -2$$

$$x_2 = \frac{D_2}{D} = -\frac{1}{2}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ -1/2 \\ 0 \end{bmatrix}$$

$$D_3 = \begin{vmatrix} 1 & -2 & \underline{1} \\ 1 & -2 & \underline{1} \\ 3 & -2 & \underline{1} \end{vmatrix} = 0$$

$$x_3 = \frac{D_3}{D} = 0$$

3 x 3 systems

If we can find an inverse of a 3x3 matrix, we can solve 3x3 (or higher) systems:

$$x_1 - 2x_2 + 2x_3 = 1$$

$$x_1 - 2x_2 + x_3 = 1$$

$$3x_1 - 2x_2 + x_3 = 1$$

Put the equations in matrix form:

$$\begin{pmatrix} 1 & -2 & 2 \\ 1 & -2 & 1 \\ 3 & -2 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

Multiply by the inverse *from the left* :

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 & -2 & 2 \\ 1 & -2 & 1 \\ 3 & -2 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

Finding the inverse of a 3 x 3 matrix

The inverse can be found by using a series of row operations.
Any system of equations is unchanged by:

- Multiplying a row by a scalar
- Adding a multiple of one row to another
- Swapping any two rows

$$x_1 \quad -2x_2 \quad +2x_3 \quad = \quad 1$$

$$x_1 \quad -2x_2 \quad +x_3 \quad = \quad 1$$

$$3x_1 \quad -2x_2 \quad +x_3 \quad = \quad 1$$

Steps to find the inverse of an $n \times n$ matrix:

1. "Augment" the matrix:

$$\begin{pmatrix} 1 & -2 & 2 \\ 1 & -2 & 1 \\ 3 & -2 & 1 \end{pmatrix} \quad \rightarrow \quad \left(\begin{array}{ccc|ccc} 1 & -2 & 2 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 & 1 & 0 \\ 3 & -2 & 1 & 0 & 0 & 1 \end{array} \right)$$

2. Use row operations to transform the left half into the identity.
The right half will then be the inverse.

Example: find the inverse of $\begin{pmatrix} 1 & -2 & 2 \\ 1 & -2 & 1 \\ 3 & -2 & 1 \end{pmatrix}$

$$\left(\begin{array}{ccc|ccc}1 & -2 & 2 & 1 & 0 & 0 \\1 & -2 & 1 & 0 & 1 & 0 \\3 & -2 & 1 & 0 & 0 & 1\end{array}\right)$$

Alternate method for finding the inverse:

1. Compute the matrix of cofactors **C**

The cofactors are the signed determinants of the small matrices.

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

2. *Transpose* this to form the Adjugate matrix $\text{Adj}(\mathbf{A})$

3. The inverse is then

$$\mathbf{A}^{-1} = \frac{1}{\det \mathbf{A}} \text{Adj } \mathbf{A}$$

Example: Find the inverse of

$$\mathbf{A} = \begin{pmatrix} 2 & 1 & 2 \\ 0 & 1 & 3 \\ 3 & 0 & 1 \end{pmatrix}$$

$$\mathbf{A}^{-1} = \frac{1}{\det \mathbf{A}} \text{Adj } \mathbf{A}$$

$$\begin{aligned} \det \begin{pmatrix} 2 & 1 & 2 \\ 0 & 1 & 3 \\ 3 & 0 & 1 \end{pmatrix} &= 2 \begin{vmatrix} 1 & 3 \\ 0 & 1 \end{vmatrix} - \begin{vmatrix} 0 & 3 \\ 3 & 1 \end{vmatrix} + 2 \begin{vmatrix} 0 & 1 \\ 3 & 0 \end{vmatrix} = \\ &= 2(1-0) - (-9) - 6 = 5 \end{aligned}$$

$$\mathbf{A} = \begin{pmatrix} 2 & 1 & 2 \\ 0 & 1 & 3 \\ 3 & 0 & 1 \end{pmatrix}$$

$$\mathbf{A}^{-1} = \frac{1}{\det \mathbf{A}} \text{Adj } \mathbf{A}$$

$$\mathbf{A}^c = \begin{pmatrix} \begin{vmatrix} 1 & 3 \\ 0 & 1 \end{vmatrix} & -\begin{vmatrix} 0 & 3 \\ 3 & 1 \end{vmatrix} & \begin{vmatrix} 0 & 1 \\ 3 & 0 \end{vmatrix} \\ -\begin{vmatrix} 1 & 2 \\ 0 & 1 \end{vmatrix} & \begin{vmatrix} 2 & 2 \\ 3 & 1 \end{vmatrix} & -\begin{vmatrix} 2 & 1 \\ 3 & 0 \end{vmatrix} \\ \begin{vmatrix} 1 & 2 \\ 1 & 3 \end{vmatrix} & -\begin{vmatrix} 2 & 2 \\ 0 & 3 \end{vmatrix} & \begin{vmatrix} 2 & 1 \\ 0 & 1 \end{vmatrix} \end{pmatrix} = \begin{pmatrix} 1 & 9 & -3 \\ -1 & -4 & 3 \\ 1 & -6 & 2 \end{pmatrix}$$

$$\text{Adj } \mathbf{A} = [\mathbf{A}^c]^T = \begin{pmatrix} 1 & -1 & 1 \\ 9 & -4 & -6 \\ -3 & 3 & 2 \end{pmatrix}$$

$$\mathbf{A}^{-1} = \frac{1}{5} \begin{pmatrix} 1 & -1 & 1 \\ 9 & -4 & -6 \\ -3 & 3 & 2 \end{pmatrix}$$

The determinant of a 2x2 matrix is written

$$\Delta = ad - bc$$

If $\Delta=0$, there is *no unique solution* to the equations $\mathbf{A} \mathbf{x} = \mathbf{b}$.

E.g. Consider the system

$$\begin{array}{rcrcrcrcrcl} x_1 & + & x_2 & = & 5 \\ x_1 & + & x_2 & = & 1 \end{array}$$

$$\mathbf{A} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \quad \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \quad \mathbf{b} = \begin{pmatrix} 5 \\ 1 \end{pmatrix}$$

Definition:

A linear 3 by 3 system with zeros *below* the main diagonal is said to be in row-echelon form.

This can be solved using *back-substitution*.

$$\left[\begin{array}{ccc|c} 1 & 2 & 1 & 11 \\ 0 & -3 & 1 & 25 \\ 0 & 0 & 2 & 70 \end{array} \right]$$

A matrix can be put into row-echelon form using *Row-operations*. This is known as Gauss elimination.

Example: For the system

$$-x_1 + x_2 + 2x_3 = 2$$

$$3x_1 - x_2 + x_3 = 6$$

$$-x_1 + 3x_2 + 4x_3 = 4$$

The augmented matrix is

$$\left[\begin{array}{ccc|c} -1 & 1 & 2 & 2 \\ 3 & -1 & 1 & 6 \\ -1 & 3 & 4 & 4 \end{array} \right]$$

Any system of equations is unchanged by:

- Multiplying a row by a scalar
- Adding a multiple of one row to another
- Swapping any two rows

Under/overspecification of a problem

Example: Does this system of equations have a (unique) solution?

$$2x_1 + x_2 = 1$$

$$x_1 + 2x_2 + x_3 = -1$$

$$+ 3x_2 + 2x_3 = 1$$

We might think so, but here the situation is more complicated than simply having three equations and three unknowns.

Under/overspecification of a problem

Example: Does this system of equations have a (unique) solution?

$$2x_1 + x_2 = 1$$

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$$+3x_2 + 2x_3 = -3$$

We might think so, but here the situation is more complicated than simply having three equations and three unknowns.