

Calculus of Several Variables

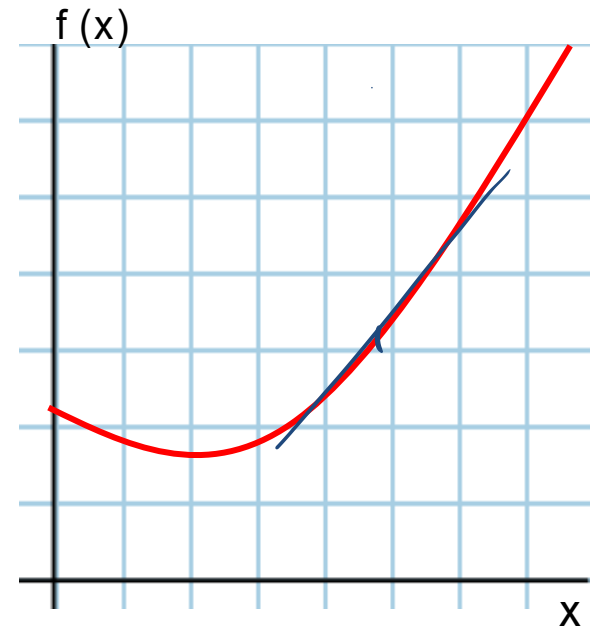
Content

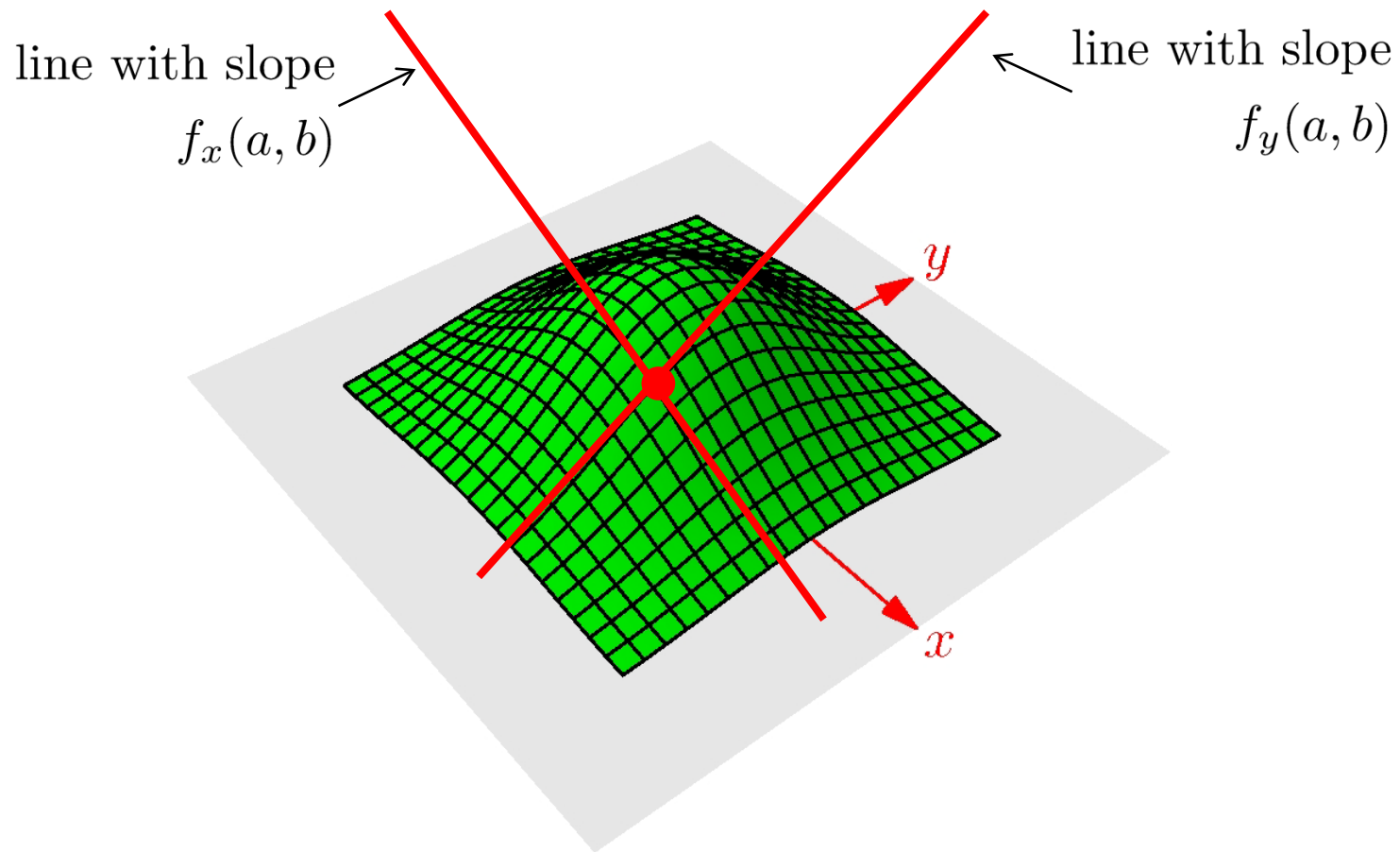
- Tangent plane
- Linear approximations
- Differentials
- Chain rule

Tangent lines and planes

Recall that for a function of a single variable $y=f(x)$, we can find the equation of a tangent line at a point x_0 from the derivative $f'(x_0)$:

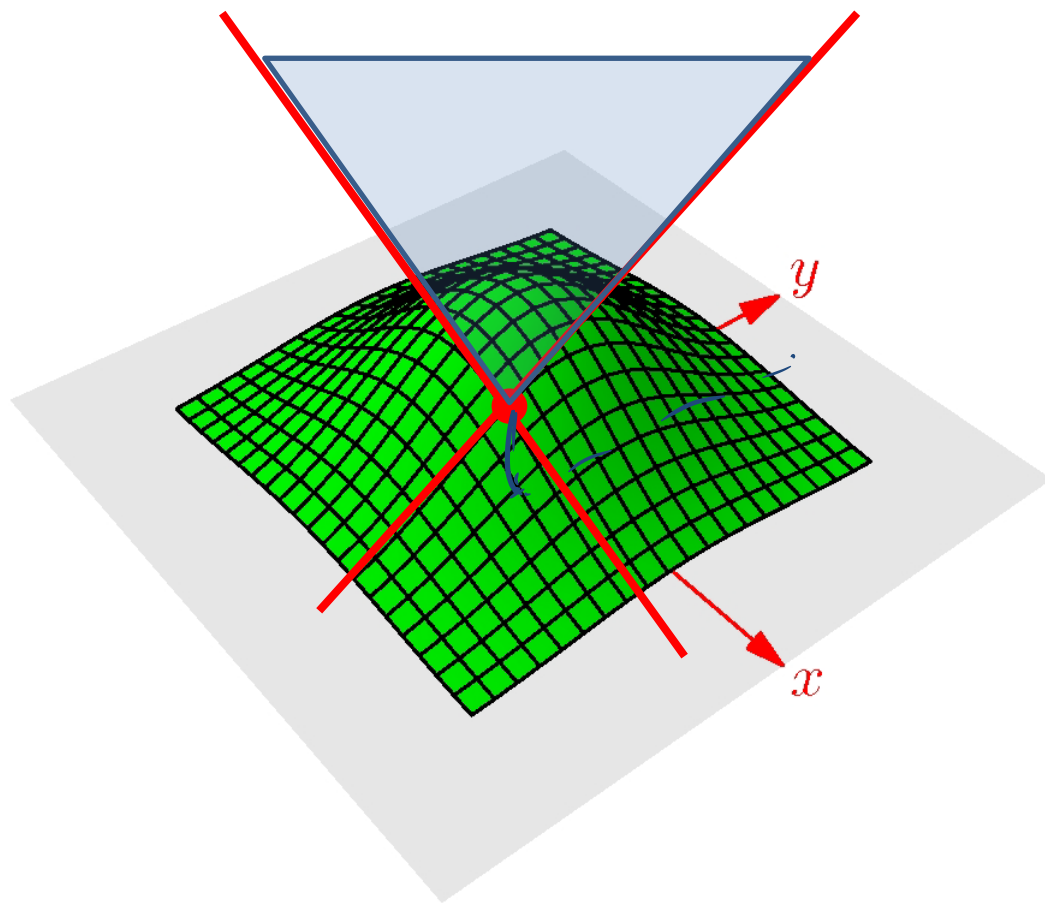
$$y - f(x_0) = f'(x_0)(x - x_0)$$





For a two-variable function $f(x,y)$ the *tangent plane* to the function at a given point (a,b) is given by the equation

$$z - f(a, b) = f_x(a, b)(x - a) + f_y(a, b)(y - b)$$



Example: Find the tangent plane to the surface

$$z = e^{-x^2-y^2}$$

at the point $(1,1)$.

$$f(1,1) = e^{-1-1} = \frac{1}{e^2}$$

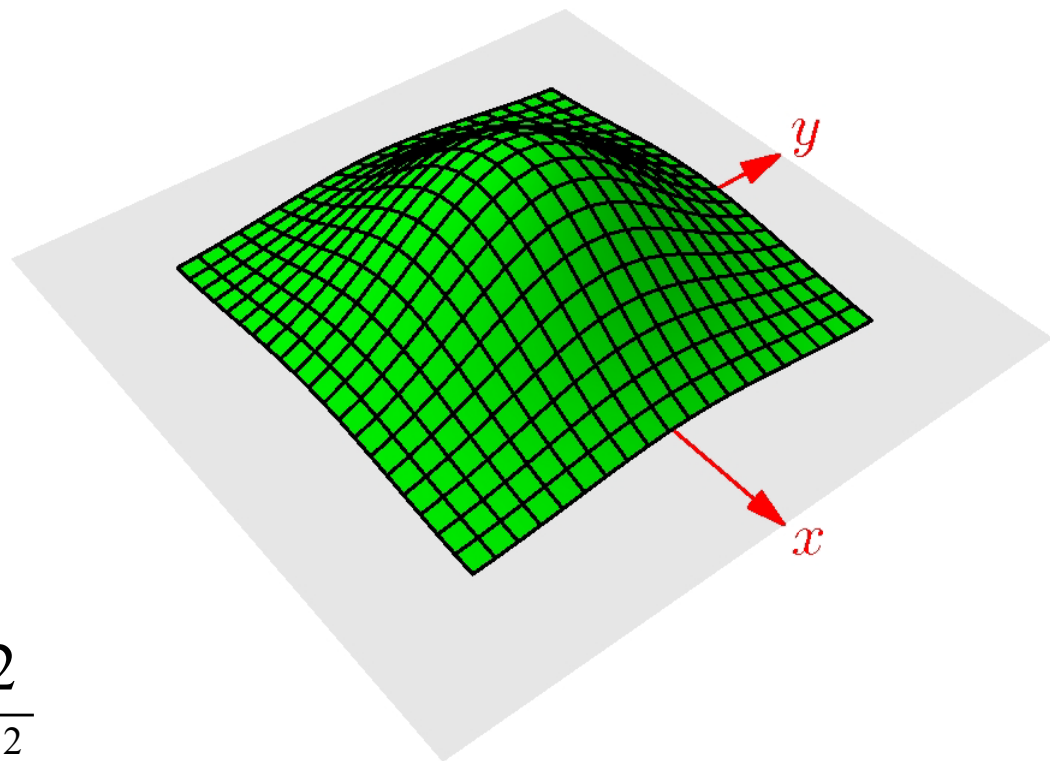
$$f_x = -2xe^{-x^2-y^2}, f_x(1,1) = -\frac{2}{e^2}$$

$$f_y = -2ye^{-x^2-y^2}, f_y(1,1) = -\frac{2}{e^2}$$

$$z - \frac{1}{e^2} = -\frac{2}{e^2}(x-1) - \frac{2}{e^2}(y-1)$$

$$e^2 z - 1 = -2x + 2 - 2y + 2$$

$$2x + 2y + e^2 z = 5$$



Example: Find the tangent plane to the surface

$$z = x^2 - y^2$$

at the point $(0,1)$.

$$f(0,1) = -1$$

$$f_x = 2x, f_x(0,1) = 0$$

$$f_y = -2y, f_y(0,1) = -2$$

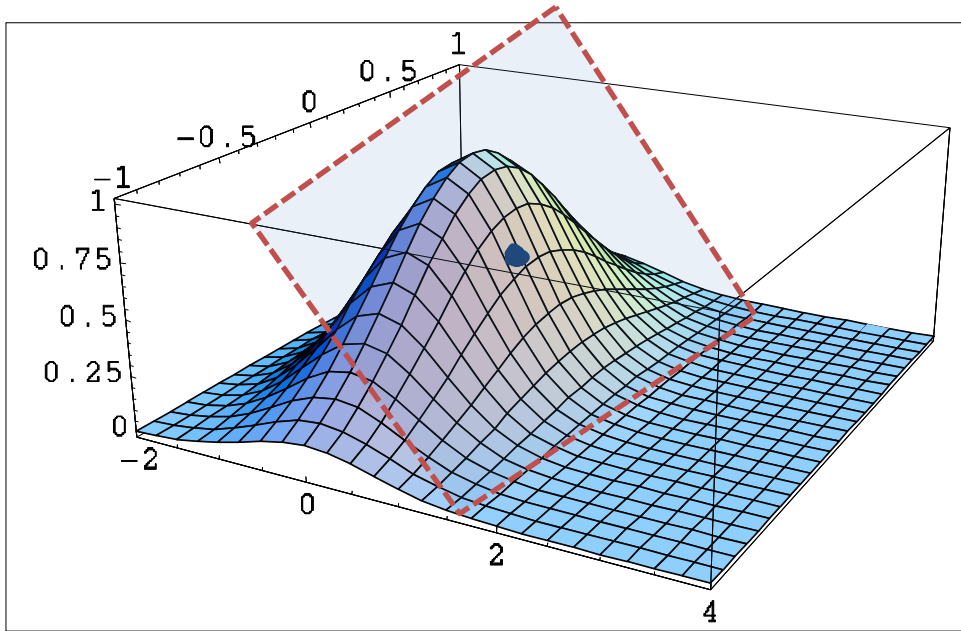
$$z + 1 = 0(x - 0) - 2(y - 1)$$

$$z + 1 = -2y + 2$$

$$2y + z = 1$$

Linear approximation

The tangent plane and the function $f(x,y)$ have very similar values near the point of contact



This means that the equation of the tangent plane

$$z = L(x, y)$$

can be regarded as an approximation for $f(x,y)$.

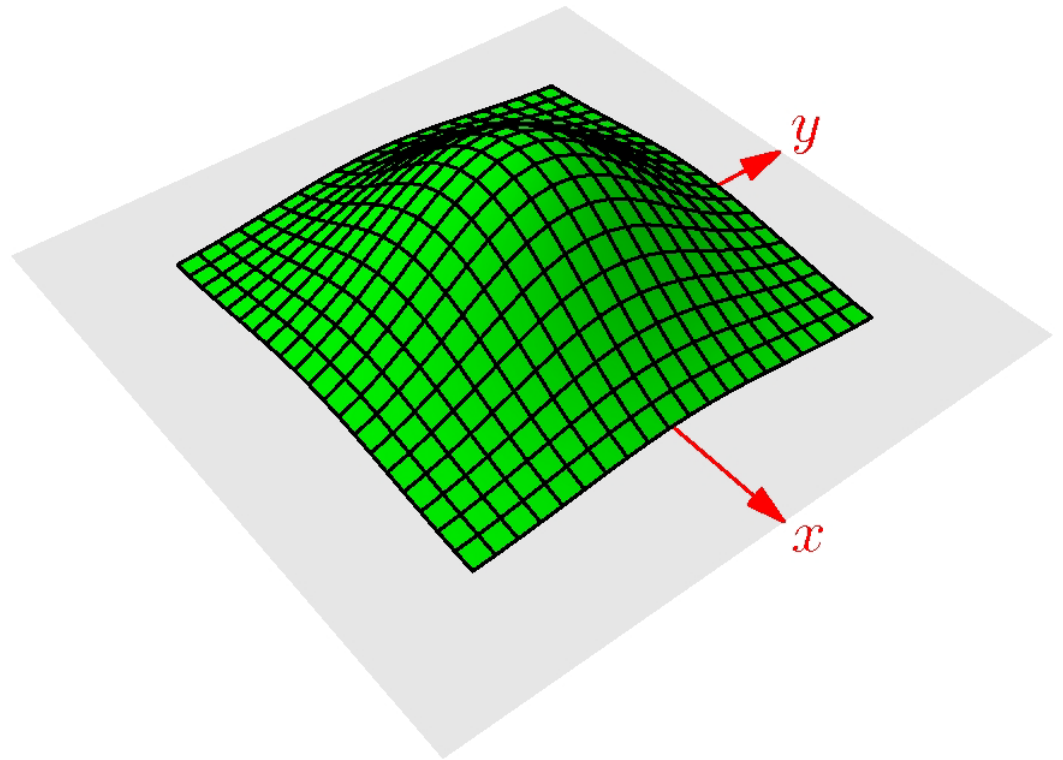
Rewriting the equation of the plane, we find:

$$L(x, y) = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$$

Example: Find a linear approximation for the function near the point $(1,1)$.

$$f(x, y) = e^{-x^2 - y^2}$$

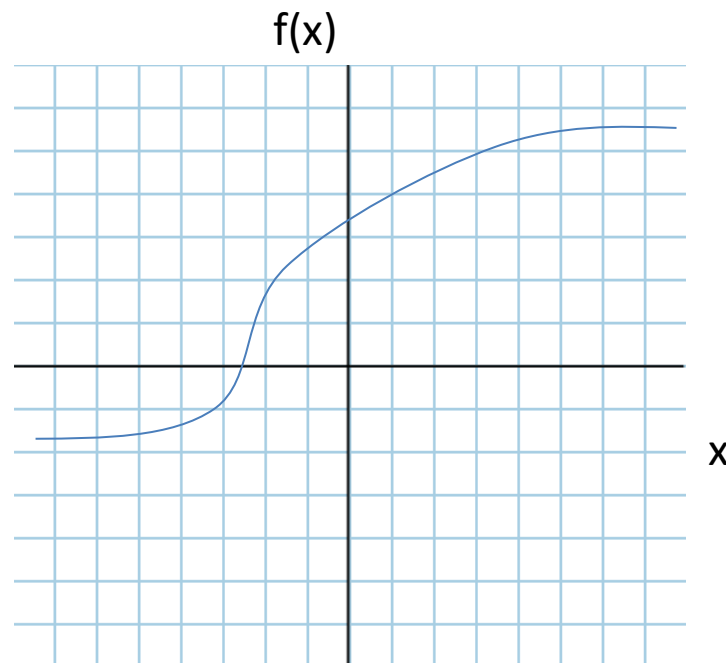
Construct the tangent plane at $(1,1)$



Differentials

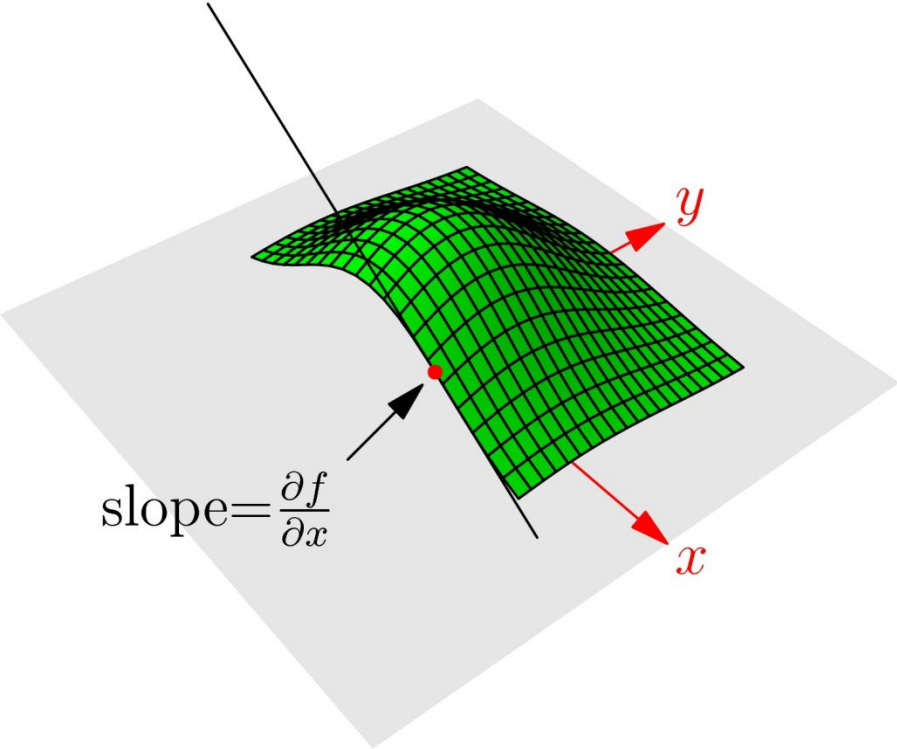
For a single variable function $f(x)$, the *differential* df is the change in the function for a small change in x :

$$df = \frac{df}{dx} dx$$



- The differentials df and dx can be thought of as changes in f and x taken *in the limit that both become very small*

Can we do the same thing for functions of two variables?

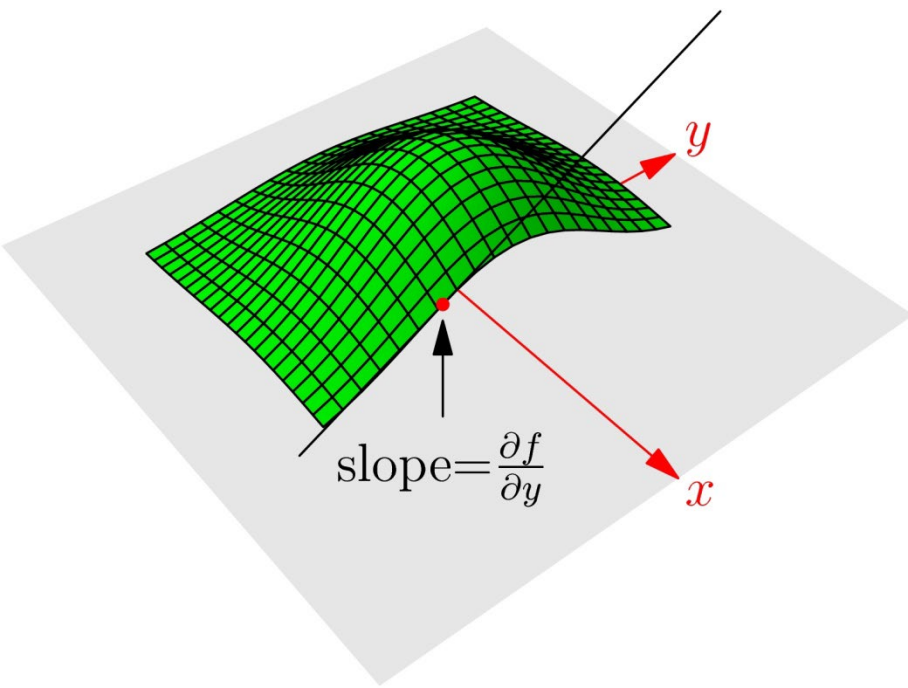


For a small step dx in the x direction
the function changes by

$$df = \frac{\partial f}{\partial x} dx$$

For a small step dy in the y direction
the function changes by

$$df = \frac{\partial f}{\partial y} dy$$



Therefore for a change in position
in *both* dx and dy the function changes by

Definition:

For a differentiable function $f(x,y)$, we define the *total differential* df as

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

where the quantities dx and dy represent infinitesimal changes in x and y .

Example:

Find the total differential of $f(x,y) = e^{-x} \sin(y+2x)$.

$$f_x = -e^{-x} \sin(y + 2x) + 2e^{-x} \cos(y + 2x)$$

$$f_y = e^{-x} \cos(y + 2x)$$

$$df = f_x dx + f_y dy =$$

$$(-e^{-x} \sin(y + 2x) + 2e^{-x} \cos(y + 2x))dx + e^{-x} \cos(y + 2x)dy$$

The chain rule with one independent variable

Suppose that $z = f(x, y)$ is a differentiable function of x and y , and that $x = x(t)$ and $y = y(t)$ are both differentiable functions of t .
 $z = f(x(t), y(t))$

From the differential

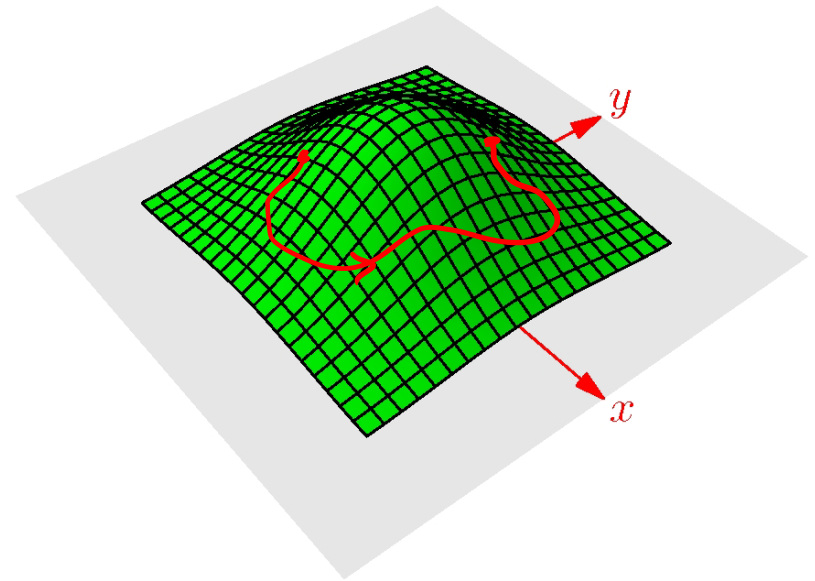
$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

we obtain the *chain rule*

$$\frac{df}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}$$

(x, y) are called *intermediate variables*.

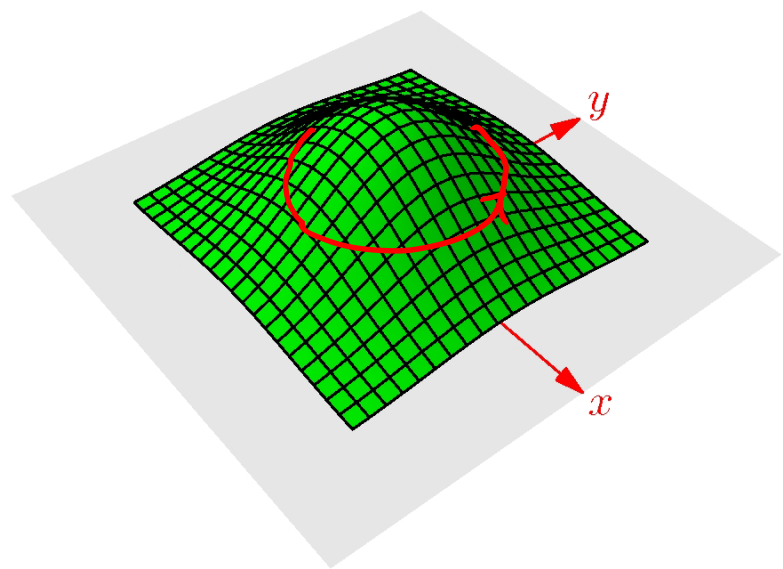
t is the only *independent variable*.



Example: Let

$$z = f(x, y) = e^{-x^2 - y^2}$$

and let $x(t) = \cos t$, $y(t) = \sin t$. Compute dz/dt .



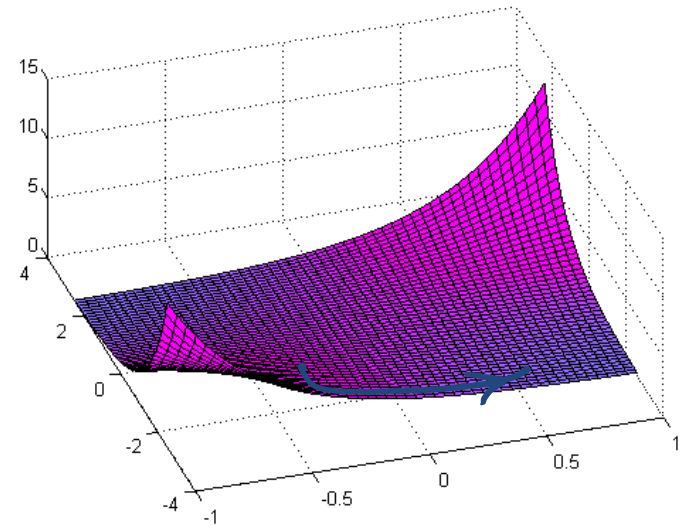
$$\begin{aligned} \frac{dz}{dt} &= \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} = -2xe^{-x^2 - y^2} (-)\sin t - 2ye^{-x^2 - y^2} \cos t = \\ &= 2e^{-x^2 - y^2} (x \sin t - y \cos t) = 2e^{-x^2 - y^2} (\cos t \sin t - \sin t \cos t) = 0 \end{aligned}$$

Example: Let

$$z = f(x, y) = e^{xy}$$

and let $x(t) = t^2$, $y(t) = t^3$.

Compute dz/dt .



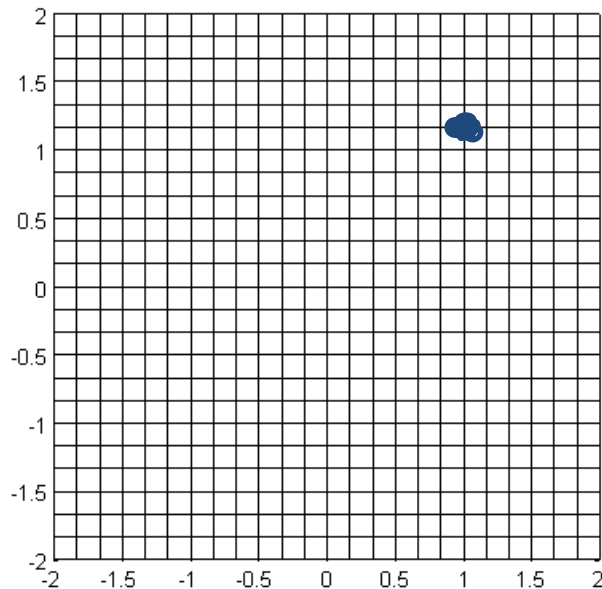
$$\frac{dz}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} = ye^{xy} 2t + xe^{xy} 3t^2 = t^3 e^{xy} 2t + t^2 e^{xy} 3t^2 = 5t^4 e^{t^5}.$$

Changing coordinates

Suppose now that $x = x(s,t)$ and $y = y(s,t)$ are themselves functions of *new independent variables* s and t .

The new variables (s,t) also describe points in 2D space.

Old coordinate system (x,y)



$$s = s(x, y)$$

$$t = t(x, y)$$

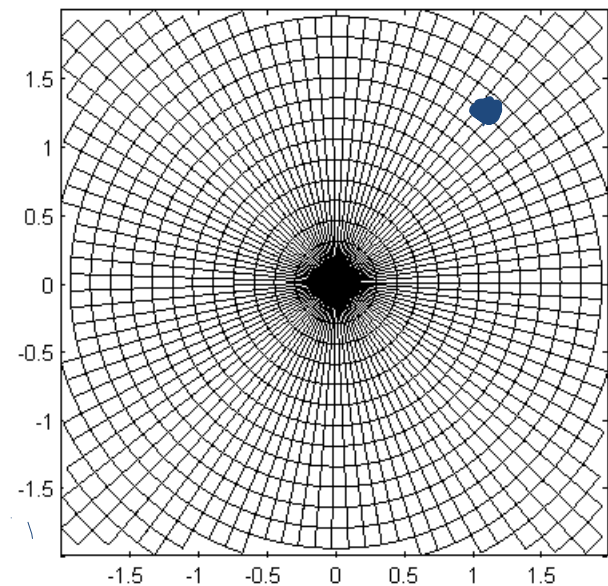


$$x = x(s, t)$$

$$y = y(s, t)$$



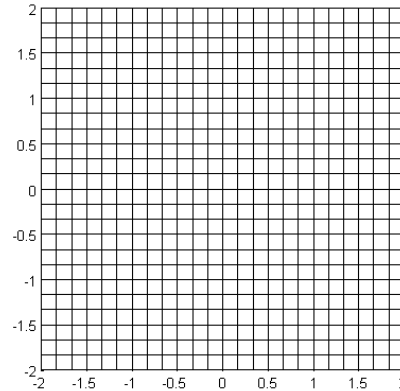
New coordinate system (s,t)



To move derivatives from one coordinate system to another we use the *chain rule for two independent variables*:

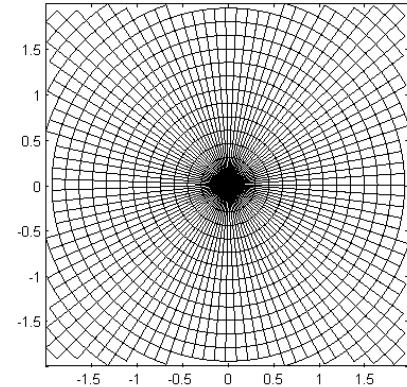
$$\frac{\partial f}{\partial s} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s}$$

$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial t}$$



$$x = x(s, t)$$

$$y = y(s, t)$$



Example:

For the function $f(x, y) = e^{-x^2 - y^2}$

compute $\partial f / \partial r$, $\partial f / \partial \theta$ where $x = r \cos \theta$, $y = r \sin \theta$

$$\frac{\partial z}{\partial r} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial r} = -2xe^{-x^2 - y^2} \cos \theta - 2ye^{-x^2 - y^2} \sin \theta =$$

$$= -2re^{-r^2} \cos^2 \theta - 2re^{-r^2} \sin^2 \theta = -2re^{-r^2}$$

$$\begin{aligned}\frac{\partial z}{\partial \theta} &= \frac{\partial f}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial \theta} = -2xe^{-x^2-y^2}(-r)\sin\theta - 2ye^{-x^2-y^2}r\sin\theta = \\ &= 2re^{-r^2}\cos\theta\sin\theta - 2re^{-r^2}\sin\theta\cos\theta = 0\end{aligned}$$

Implicit Differentiation

Recall that a function can be defined explicitly:

$$y = f(x)$$

$$y = \pm\sqrt{4 - x^2}$$

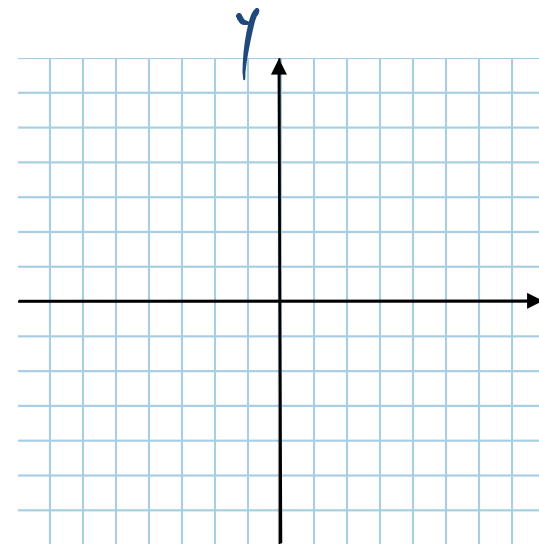
or implicitly:

$$F(x, y) = 0$$

$$x^2 + y^2 = 4$$

Now let $x = t$, and $y = y(x) = y(x(t))$.

Then using the chain rule on $F(x, y)$, we can find dy/dx :

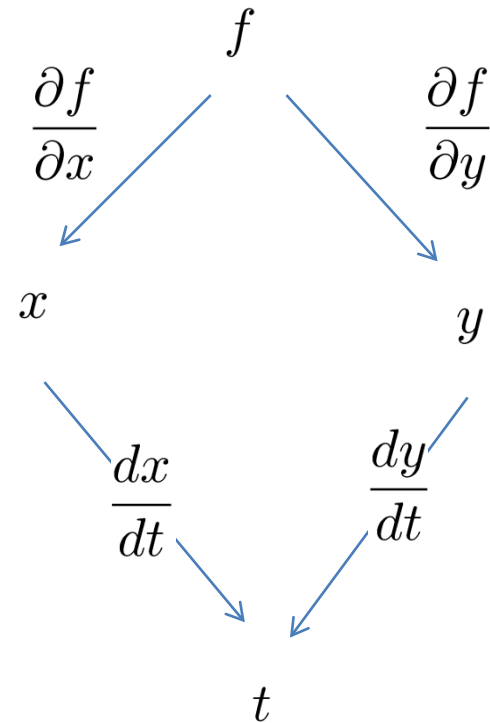


$$\frac{dy}{dx} = -\frac{F_x}{F_y}$$

Example: Find y' if $x^3 - 2xy + y^2 = 1$.

We can remember the chain rule using a tree diagram:

f
is a function of
 x and y
which are functions of
 t



How to remember the chain rule for two independent variables:

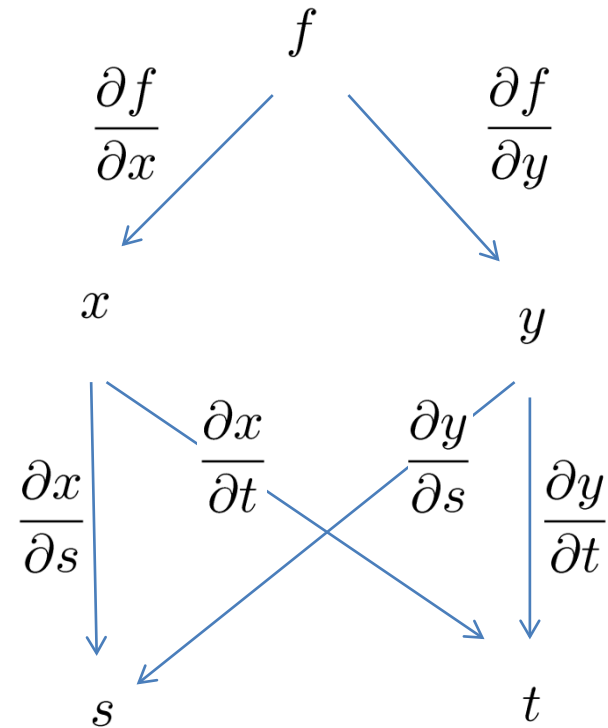
f

is a function of

x and y

which are functions of

s and t



General formulation of the chain rule:

Suppose that $u(x_1, x_2, x_3, \dots, x_n)$ is a differentiable function of the n variables $x_1, x_2, x_3, \dots, x_n$.

And each $x_j(t_1, t_2, \dots, t_m)$ is a differentiable function of the m variables t_1, t_2, \dots, t_m .

Then the derivative of u with respect to each of the t_i variables is

$$\frac{\partial u}{\partial t_i} = \frac{\partial u}{\partial x_1} \frac{\partial x_1}{\partial t_i} + \frac{\partial u}{\partial x_2} \frac{\partial x_2}{\partial t_i} + \dots + \frac{\partial u}{\partial x_n} \frac{\partial x_n}{\partial t_i}$$

Note that we can write this in matrix form, where **J** is transition (Jacobian) matrix

$$\begin{pmatrix} \frac{\partial u}{\partial t_1} \\ \frac{\partial u}{\partial t_2} \\ \vdots \\ \frac{\partial u}{\partial t_m} \end{pmatrix} = \begin{pmatrix} \frac{\partial x_1}{\partial t_1} & \frac{\partial x_2}{\partial t_1} & \dots & \frac{\partial x_n}{\partial t_1} \\ \frac{\partial x_1}{\partial t_2} & \frac{\partial x_2}{\partial t_2} & \dots & \frac{\partial x_n}{\partial t_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x_1}{\partial t_m} & \frac{\partial x_2}{\partial t_m} & \dots & \frac{\partial x_n}{\partial t_m} \end{pmatrix} \begin{pmatrix} \frac{\partial u}{\partial x_1} \\ \frac{\partial u}{\partial x_2} \\ \vdots \\ \frac{\partial u}{\partial x_n} \end{pmatrix}, \mathbf{J} = \begin{pmatrix} \frac{\partial x_1}{\partial t_1} & \frac{\partial x_2}{\partial t_1} & \dots & \frac{\partial x_n}{\partial t_1} \\ \frac{\partial x_1}{\partial t_2} & \frac{\partial x_2}{\partial t_2} & \dots & \frac{\partial x_n}{\partial t_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x_1}{\partial t_m} & \frac{\partial x_2}{\partial t_m} & \dots & \frac{\partial x_n}{\partial t_m} \end{pmatrix}$$

$$\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} = 0, \quad \text{Laplacian of function } U(x, y)$$

Find Laplacian in cylindrical coordinate system

$$x = r \cos \theta, \quad y = r \sin \theta$$

$$U(x, y) = U(r \cos \theta, r \sin \theta) = \tilde{U}(r, \theta) = \tilde{U}(r(x, y), \theta(x, y))$$

$$\frac{\partial U}{\partial x} = \frac{\partial \tilde{U}}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial \tilde{U}}{\partial \theta} \frac{\partial \theta}{\partial x} = \tilde{U}_r \frac{\partial r}{\partial x} + \tilde{U}_\theta \frac{\partial \theta}{\partial x}$$

$$\frac{\partial^2 U}{\partial x^2} = \frac{\partial}{\partial x} \frac{\partial U}{\partial x} = \frac{\partial}{\partial x} \left(\tilde{U}_r \frac{\partial r}{\partial x} + \tilde{U}_\theta \frac{\partial \theta}{\partial x} \right) = \frac{\partial \tilde{U}_r}{\partial x} \frac{\partial r}{\partial x} + \tilde{U}_r \frac{\partial^2 r}{\partial x^2} +$$

$$+ \frac{\partial \tilde{U}_\theta}{\partial x} \frac{\partial \theta}{\partial x} + \tilde{U}_\theta \frac{\partial^2 \theta}{\partial x^2} = \frac{\partial r}{\partial x} \left(\frac{\partial \tilde{U}_r}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial \tilde{U}_r}{\partial \theta} \frac{\partial \theta}{\partial x} \right) + \tilde{U}_r \frac{\partial^2 r}{\partial x^2} +$$

$$+ \frac{\partial \theta}{\partial x} \left(\frac{\partial \tilde{U}_\theta}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial \tilde{U}_\theta}{\partial \theta} \frac{\partial \theta}{\partial x} \right) + \tilde{U}_\theta \frac{\partial^2 \theta}{\partial x^2} = \frac{\partial^2 \tilde{U}}{\partial r^2} \left(\frac{\partial r}{\partial x} \right)^2 + \frac{\partial^2 \tilde{U}}{\partial \theta \partial r} \frac{\partial \theta}{\partial x} \frac{\partial r}{\partial x} + \frac{\partial \tilde{U}}{\partial r} \frac{\partial^2 r}{\partial x^2}$$

$$+ \frac{\partial^2 \tilde{U}}{\partial \theta^2} \left(\frac{\partial \theta}{\partial x} \right)^2 + \frac{\partial^2 \tilde{U}}{\partial r \partial \theta} \frac{\partial \theta}{\partial x} \frac{\partial r}{\partial x} + \frac{\partial \tilde{U}}{\partial \theta} \frac{\partial^2 \theta}{\partial x^2}$$

$$\frac{\partial U}{\partial y} = \frac{\partial \tilde{U}}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial \tilde{U}}{\partial \theta} \frac{\partial \theta}{\partial y} = \tilde{U}_r \frac{\partial r}{\partial y} + \tilde{U}_\theta \frac{\partial \theta}{\partial y}$$

$$\frac{\partial^2 U}{\partial y^2} = \frac{\partial}{\partial y} \frac{\partial U}{\partial y} = \frac{\partial}{\partial y} \left(\tilde{U}_r \frac{\partial r}{\partial y} + \tilde{U}_\theta \frac{\partial \theta}{\partial y} \right) = \frac{\partial \tilde{U}_r}{\partial y} \frac{\partial r}{\partial y} + \tilde{U}_r \frac{\partial^2 r}{\partial y^2} +$$

$$+ \frac{\partial \tilde{U}_\theta}{\partial y} \frac{\partial \theta}{\partial y} + \tilde{U}_\theta \frac{\partial^2 \theta}{\partial y^2} = \frac{\partial r}{\partial y} \left(\frac{\partial \tilde{U}_r}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial \tilde{U}_r}{\partial \theta} \frac{\partial \theta}{\partial y} \right) + \tilde{U}_r \frac{\partial^2 r}{\partial y^2} +$$

$$+ \frac{\partial \theta}{\partial y} \left(\frac{\partial \tilde{U}_\theta}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial \tilde{U}_\theta}{\partial \theta} \frac{\partial \theta}{\partial y} \right) + \tilde{U}_\theta \frac{\partial^2 \theta}{\partial y^2} = \frac{\partial^2 \tilde{U}}{\partial r^2} \left(\frac{\partial r}{\partial y} \right)^2 + \frac{\partial^2 \tilde{U}}{\partial \theta \partial r} \frac{\partial \theta}{\partial x} \frac{\partial r}{\partial y} + \frac{\partial \tilde{U}}{\partial r} \frac{\partial^2 r}{\partial y^2}$$

$$+ \frac{\partial^2 \tilde{U}}{\partial \theta^2} \left(\frac{\partial \theta}{\partial y} \right)^2 + \frac{\partial^2 \tilde{U}}{\partial r \partial \theta} \frac{\partial \theta}{\partial y} \frac{\partial r}{\partial y} + \frac{\partial \tilde{U}}{\partial \theta} \frac{\partial^2 \theta}{\partial y^2} =$$

$$\frac{\partial^2 \tilde{U}}{\partial r^2} \left(\frac{\partial r}{\partial y} \right)^2 + 2 \frac{\partial^2 \tilde{U}}{\partial \theta \partial r} \frac{\partial \theta}{\partial x} \frac{\partial r}{\partial y} + \frac{\partial \tilde{U}}{\partial r} \frac{\partial^2 r}{\partial y^2} + \frac{\partial^2 \tilde{U}}{\partial \theta^2} \left(\frac{\partial \theta}{\partial y} \right)^2 + \frac{\partial \tilde{U}}{\partial \theta} \frac{\partial^2 \theta}{\partial y^2}$$

$$\frac{\partial r}{\partial x} = \frac{\partial (x^2 + y^2)^{1/2}}{\partial x} = \frac{x}{(x^2 + y^2)^{1/2}} = \cos \theta$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial \arctan \frac{y}{x}}{\partial x} = \frac{1}{1 + \left(\frac{y}{x}\right)^2} \frac{-y}{x^2} = -\frac{y}{x^2 + y^2} = -\frac{\sin \theta}{r}$$

$$\frac{\partial r}{\partial y} = \frac{\partial (x^2 + y^2)^{1/2}}{\partial y} = \frac{y}{(x^2 + y^2)^{1/2}} = \sin \theta$$

$$\frac{\partial \theta}{\partial y} = \frac{\partial \arctan \frac{y}{x}}{\partial y} = \frac{1}{1 + \left(\frac{y}{x}\right)^2} \frac{1}{x} = \frac{x}{x^2 + y^2} = \frac{\cos \theta}{r}$$

$$\frac{\partial^2 r}{\partial x^2} = \frac{\partial}{\partial x} \frac{\partial r}{\partial x} = \frac{\partial \cos \theta}{\partial x} = -\sin \theta \frac{\partial \theta}{\partial x} = \frac{\sin^2 \theta}{r}$$

$$\frac{\partial^2 \theta}{\partial x^2} = \frac{\partial}{\partial x} \frac{\partial \theta}{\partial x} = -\frac{\partial}{\partial x} \frac{\sin \theta}{r} = -\sin \theta \frac{\partial}{\partial x} \frac{1}{r} - \frac{1}{r} \frac{\partial \sin \theta}{\partial x} = \frac{2 \sin \theta \cos \theta}{r^2}$$

$$\frac{\partial^2 r}{\partial y^2} = \frac{\cos^2 \theta}{r}$$

$$\frac{\partial^2 \theta}{\partial y^2} = -\frac{2 \sin \theta \cos \theta}{r^2}$$

$$\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} = \frac{\partial^2 U}{\partial r^2} + \frac{1}{r} \frac{\partial U}{\partial r} + \frac{1}{r^2} \frac{\partial^2 U}{\partial \theta^2}$$