# UNIVERSITY OF TECHNOLOGY SYDNEY School of Mathematical and Physical Sciences

## 37233 LINEAR ALGEBRA

## Solutions 7

#### Question 1

(a) The domain of  $\widehat{T}$  is  $\mathbb{R}^3$  and the codomain is  $\mathbb{R}^4$ ;

(b) The image of **u** turns out to be zero element of the codomain:  $\mathbf{A}\mathbf{u} = \begin{bmatrix} 0\\0\\0\\0\end{bmatrix}$ 

(c) To find the range of  $\widehat{T}$ , we check the columns of **T** for linear independence:

$$\rightarrow \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

whereby row-reduction reveals two pivots, so the range of  $\hat{T}$  is a plane within  $\mathbb{R}^4$ , and we can select the first two vectors as its basis:

$$\mathbf{v}_1 = \begin{bmatrix} 1\\1\\1\\0 \end{bmatrix} \quad \text{and} \quad \mathbf{v}_1 = \begin{bmatrix} 0\\1\\2\\2 \end{bmatrix}$$

(d) Given the row-reduced matrix above has one free variable, the general solution for the corresponding homogeneous system is a linear combination of only one vector. We already know such a vector from part (b), which can be reconfirmed from the reduced matrix, of course. For  $\mathbf{A}\mathbf{x} = \mathbf{v}$ , the particular solution is obvious, so then any vector of the form

$$\mathbf{x}_{\mathbf{v}} = \begin{bmatrix} 1\\0\\0 \end{bmatrix} + x \begin{bmatrix} -2\\1\\1 \end{bmatrix}, \qquad \forall x \in \mathbb{R}$$

produces  ${\bf v}$  as the image.

However, an attempt to row-reduce the augmented matrix  $[\mathbf{A}\mathbf{w}]$  reveals an inconsistency

$$\rightarrow \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

therefore  $\mathbf{w}$  is not in the range of  $\mathbf{T}$  and cannot be obtained from any vector.

### Question 2

(a) The domain and codomain are  $\mathbb{R}^2$ . The columns of **T** are linearly independent (not multiples of each other), so they span  $\mathbb{R}^2$ , and the range of  $\widehat{T}$  is thus the entire  $\mathbb{R}^2$ .

(b) For the zero-corner of the square, it is obvious that the image is also zero because the transformation is linear; this also follows from multiplication. For the other corners:

$$\begin{bmatrix} 3 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \end{bmatrix}, \qquad \begin{bmatrix} 3 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}, \qquad \begin{bmatrix} 3 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 1 \end{bmatrix}$$

so the square undergoes a shear transformation with a 3-times horizontal stretch.

(c) To find the source vector  $\mathbf{x}$  given its image  $\mathbf{b}$  we need to solve the equation  $\mathbf{T}\mathbf{x} = \mathbf{b}$ . Row-reduction of the corresponding augmented matrix is straightforward:

$$\begin{bmatrix} 3 & 3 & 3 \\ 0 & 1 & 1/2 \end{bmatrix} \quad \rightarrow \quad \begin{bmatrix} 1 & 0 & 1/2 \\ 0 & 1 & 1/2 \end{bmatrix}$$

so  $\begin{bmatrix} 1/2\\ 1/2 \end{bmatrix}$  is the source vector, which is the centre of the unit square.

Quite consistently, the image is the centre of the transformed square.



#### Question 3

(a) As the transformation runs from standard vectors, the standard matrix is directly given by the columns which are vectors  $\mathbf{y}_i$ , as shown below in (b).

(b) The image is obtained as 
$$\mathbf{Tv} = \begin{bmatrix} 3 & -5 & -6 \\ 2 & 0 & 3 \\ -1 & 3 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} = \begin{pmatrix} 7 \\ 5 \\ -2 \end{pmatrix}.$$

(c) The reverse transformation matrix 
$$\mathbf{T}^{-1}$$
 is obtained by row-reducing  $[\mathbf{T}|\mathbf{I}] \rightarrow [\mathbf{I}|\mathbf{T}^{-1}]$ :

$$\begin{bmatrix} 3 & -5 & -6 & 1 & 0 & 0 \\ 2 & 0 & 3 & 0 & 1 & 0 \\ -1 & 3 & 5 & 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 3 & -5 & -6 & 1 & 0 & 0 \\ 0 & 10/3 & 7 & -2/3 & 1 & 0 \\ 0 & 0 & 1/5 & 3/5 & -2/5 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & -9/2 & 7/2 & -15/2 \\ 0 & 1 & 0 & -13/2 & 9/2 & -21/2 \\ 0 & 0 & 1 & 3 & -2 & 5 \end{bmatrix}$$

(d) The image is then obtained as 
$$\mathbf{T}^{-1}[\mathbf{u}]_{\mathcal{Y}} = \begin{bmatrix} -9/2 & 7/2 & -15/2 \\ -13/2 & 9/2 & -21/2 \\ 3 & -2 & 5 \end{bmatrix} \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix} = \begin{bmatrix} 4 \\ 5 \\ -2 \end{bmatrix}.$$

## Question 4

(a) The characteristic equation

$$0 = \det(\mathbf{A} - \lambda \mathbf{I}) = (3 - \lambda) \left( (3 - \lambda)(9 - \lambda) + 9 \right) = (3 - \lambda)(6 - \lambda)(6 - \lambda)$$

reveals  $\lambda_1 = 3$  and  $\lambda_{2,3} = 6$ .

(b) For  $\lambda_1$  the  $(\mathbf{A} - \lambda_1 \mathbf{I})\mathbf{x} = \mathbf{0}$  equation has the matrix

$$\begin{bmatrix} 0 & -3 & 0 \\ 0 & 0 & -3 \\ 0 & 3 & 6 \end{bmatrix} \to \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \mathbf{x} = x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \qquad \forall x_1 \in \mathbb{R}$$

For  $\lambda_2$  the  $(\mathbf{A} - \lambda_2 \mathbf{I})\mathbf{x} = \mathbf{0}$  equation has the matrix

$$\begin{bmatrix} -3 & -3 & 0 \\ 0 & -3 & -3 \\ 0 & 3 & 3 \end{bmatrix} \to \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \mathbf{x} = x_3 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \quad \forall x_3 \in \mathbb{R}$$

Thereby each of the vectors

$$\mathbf{v}_1 = \begin{bmatrix} 1\\0\\0 \end{bmatrix} \quad \text{and} \quad \mathbf{v}_2 = \begin{bmatrix} 1\\-1\\1 \end{bmatrix}$$

spans an eigenspace corresponding to  $\lambda_1$  and  $\lambda_2$ , respectively.