

SUPPLEMENTARY SLIDES ON LINEAR TRANSFORMATIONS

Theorem: A linear transformation $\hat{T} : \mathbb{R}^n \mapsto \mathbb{R}^m$ is a one-to-one transformation if and only if the equation $\hat{T}(\mathbf{x}) = \mathbf{0}$ has only the trivial solution $\mathbf{x} = \mathbf{0}$.

Proof: Since \hat{T} is linear then $\hat{T}(\mathbf{0}) = \mathbf{0}$. If \hat{T} is one-to-one, then the equation $\hat{T}(\mathbf{x}) = \mathbf{0}$ has at most one solution, $\mathbf{x} = \mathbf{0}$.

Suppose \hat{T} is *not* one-to-one. Then $\exists \mathbf{b} \in \mathbb{R}^m$ which is the image of at least 2 different vectors $\mathbf{u} \neq \mathbf{v}$ in \mathbb{R}^n : $\hat{T}(\mathbf{u}) = \mathbf{b}$, $\hat{T}(\mathbf{v}) = \mathbf{b}$.

But since \hat{T} is linear, $\hat{T}(\mathbf{u} - \mathbf{v}) = \hat{T}(\mathbf{u}) - \hat{T}(\mathbf{v}) = \mathbf{b} - \mathbf{b} = \mathbf{0}$.

However $\mathbf{u} - \mathbf{v} \neq \mathbf{0}$ and then the equation $\hat{T}(\mathbf{x}) = \mathbf{0}$ is going to have more than one solution: $\mathbf{0}$ and $\mathbf{u} - \mathbf{v}$.

Therefore, the assumption that \hat{T} is not one-to-one is inconsistent with only having a trivial solution, so it is one-to-one then.

Theorem: Let $\hat{T} : \mathbb{R}^n \mapsto \mathbb{R}^m$ be a linear transformation with the standard matrix \mathbf{T} . Then:

- (a) \hat{T} maps \mathbb{R}^n onto \mathbb{R}^m if and only if the columns of \mathbf{T} span \mathbb{R}^m .
- (b) \hat{T} is one-to-one if and only if the columns of \mathbf{T} are linearly independent.

Proof:

(a) The columns of \mathbf{T} span \mathbb{R}^m if and only if $\forall \mathbf{b} \in \mathbb{R}^m$ the equation $\mathbf{T}\mathbf{x} = \mathbf{b}$ is consistent, so it has a solution for every \mathbf{b} . This is true only when \hat{T} maps \mathbb{R}^n onto \mathbb{R}^m .

(b) From the previous theorem, if \hat{T} is one-to-one, the equation $\mathbf{T}\mathbf{x} = \mathbf{0}$ has only the trivial solution. This can only happen if the columns of \mathbf{T} are linearly independent.

Theorem: Let $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$ be a basis for a linear space V . Then coordinate mapping $\mathbf{x} \mapsto [\mathbf{x}]_{\mathcal{B}}$ is a one-to-one linear transformation from V onto \mathbb{R}^n .

Proof: Consider two arbitrary elements in V ,

$$\mathbf{u} = c_1 \mathbf{b}_1 + \dots + c_n \mathbf{b}_n$$

$$\mathbf{v} = d_1 \mathbf{b}_1 + \dots + d_n \mathbf{b}_n$$

Then $\mathbf{u} + \mathbf{v} = (c_1 + d_1)\mathbf{b}_1 + \dots + (c_n + d_n)\mathbf{b}_n$ and

$$[\mathbf{u} + \mathbf{v}]_{\mathcal{B}} = \begin{bmatrix} c_1 + d_1 \\ \vdots \\ c_n + d_n \end{bmatrix} = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} + \begin{bmatrix} d_1 \\ \vdots \\ d_n \end{bmatrix} = [\mathbf{u}]_{\mathcal{B}} + [\mathbf{v}]_{\mathcal{B}}$$

Thus coordinate mapping preserves addition.

Proof (continuation): If r is an arbitrary scalar, then

$$\begin{aligned} r\mathbf{u} &= r(c_1\mathbf{b}_1 + \dots + c_n\mathbf{b}_n) = \\ &= (rc_1)\mathbf{b}_1 + \dots + (rc_n)\mathbf{b}_n \end{aligned}$$

so

$$[r\mathbf{u}]_{\mathcal{B}} = \begin{bmatrix} rc_1 \\ \vdots \\ rc_n \end{bmatrix} = r \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} = r [\mathbf{u}]_{\mathcal{B}}$$

Thus coordinate mapping also preserves scalar multiplication.

Therefore, coordinate mapping $\mathbf{x} \mapsto [\mathbf{x}]_{\mathcal{B}}$ is a linear mapping.

Since \mathcal{B} is a basis, the elements $\mathbf{b}_1 \dots \mathbf{b}_n$ are linearly independent, therefore the transformation is one-to-one.