Numerical Methods 35006 Computer Lab 4: multi-dimensional minimisation

The aim of this lab is to guide you through the steps of creating a Powell Direction-Set multidimensional search procedure. It relies on successful implementation of the bracketing and golden searched from last week.

1. Surfaces in 2D can be imaged using both color and contour plots. To enable this it is helpful to use *np.meshgrid*. This takes two arrays generated by linspace and creates an array of 2D coordinates.

a) Use linspace to generate an array of 5 x values and an array of 10 y values in the ranges $x \in [0,2]$ and $y \in [0,5]$. Generate a grid by typing

X,Y = np.meshgrid(x,y)

- b) Now generate a 100×100 grid of points (X,Y) in the range $x \in [-2, 2]$ and $y \in [-2, 2]$.
- c) Use the pyplot plotting command pcolor

plt.pcolor(X,Y,np.exp(-X**2 - Y**2))

to make sure your plotting is working properly.

2. Use the pyplot command plt.contour to plot a contour map of the function

$$f(x,y) = (x-1)^2 + y^2$$
(1)

in the range $x \in [-2, 2], y \in [-1, 1].$

Define the function f(x,y) as in Q2 above. Import the 3D Axes module Axes3D to plot this function as a surface plot:

from mpl_toolkits.mplot3d import Axes3D
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
surf = ax.plot_surface(X, Y, f(X,Y))

4. Building on your code in Q3, create code that, given a vector starting point $\mathbf{xn} = [-2, -1]$ and a direction $\mathbf{pn} = [1, 0]$, plots 20 points along a line starting at \mathbf{xn} and going in the direction \mathbf{pn} , with a stepsize of h = 0.2 between each point, according to

$$\mathbf{x} = \mathbf{x}_n + t\mathbf{p}_n \tag{2}$$

- 5. Building on your code in Q4, create a function fline(t), that returns the value of f for a particular value of t, according to Eq. (2). Bracket the minima along this curve using your search routine from last week, then find the minimum to within a tolerance of 10^{-5} using a golden section search.
- 6. Add two loops to your code: one to search over a set of orthogonal directions, which are stored in a matrix pset. The other loop should iterate these two searches until a minimum is found (or the minimum is lost).
- 7. Finally, update the set of coordinate directions at the end of each iteration to create a powell search algorithm, as given in the lecture slides. Test this with a few different starting points on the function given in Eq. (1).
- Create a function called powellsearch(f,x0), which finds the minimum of a 2D function f from a starting point x0. Incorporate this routine into your mysearch.py module.